# How to make my Air Glide S work properly

Originally written by Horst Rupp.

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The basic prerequisite for the Air Glide S, in particular the AHRS part, to work properly so that the extraneous 'noise' (gusts, wind shifts, perturbations etc) can be removed is to ensure that it is set up correctly. The instrument is very sensitive and the installation needs to be done in a way that ensures that only the correct inputs are being sensed.

Most legacy instrument installations take all pressures from probes at the rudder fin. And most unfortunately, many of them use the total energy (TE) pressure from the fin to feed in parallel a mass-measurement variometer with a capacity flask (in Germany mostly a Winter) and a pressure sensor probe variometer such as the Air Glide S (no capacity flask).

There are many publications indicating the deterioration (mostly damping) of the pressure sensor probe measurements by the stream of air mass in and out of the capacity flask. So, it is obviously a somewhat bad idea to do that to your Air Glide S. This interference with a mass measuring instruments is certainly not compliant with the above mentioned basic prerequisite.

Fortunately, the Air Glide S can be compensated by total pressure (called electronic compensation as opposed to TE compensation). This is a new feature of the Air Glide S arriving with V 1.1.

Total pressure and TE pressure carry more or less (depends on quality of probe) the same information - but for the sign : Total pressure is static pressure PLUS pitot pressure, TE pressure is static pressure MINUS pitot pressure (probe compensation factor (~)-1).

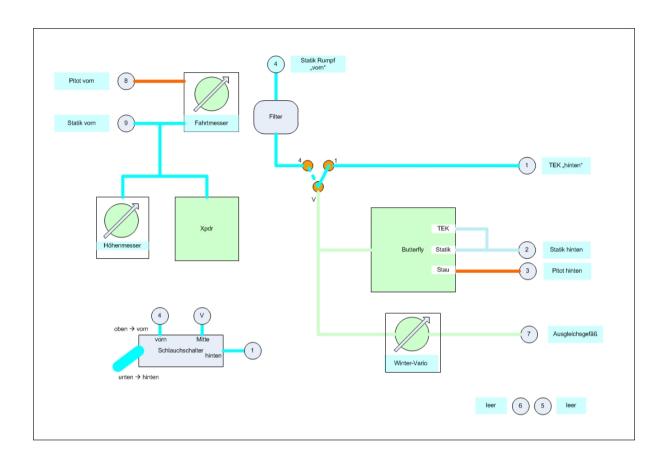
Thus, for a modern flight computer like in the Air Glide S it is no problem to derive the compensation signal from total pressure (electronic compensation).

The advantage of electronic compensation is twofold: It makes the tubing so much simpler and it gets rid of the above mentioned deterioration.

You may reserve the existing TE compensation pressure for the mass measuring variometer, as in legacy installations, but there is no need for a TE compensation pressure connection necessary at the Air Glide S.

If you go that avenue, you will end up with a "free" inlet at the Air Glide S sensor box. This inlet should then be connected to static pressure (in parallel to the dedicated "static" pressure inlet. In the Air Glide S setup there is a setting to tell the instrument it should use the electronic compensation method. The appropriate value in the Air Glide S setup has to be set to 100% (see details below).

According to my experience the vario function of Air Glide S speeds up by a factor of 2 - 3 when the TE probe is disconnected from a mass-measuring variometer and electronic compensation is used instead. In my plane I had to increase the damping factors.



The most crucial point for the proper functioning of your Air Glide S is where and how the Air Glide S sensor box is fitted to your ship. The place to put the box must be free of all varying magnetic fields, be it the compass, moving magneto-metallic parts, or electrical gear or cables which run a lot of current and are switched on and off intermittently or periodically.

There is an immediate yet coarse test for this condition. Switch to the horizon page and observe the compass course indication. Now move flaps, gear and brakes and rudder. The compass should stay stable. Then (except for the Air Glide S itself <sup>©</sup>) switch on and off your electronic gadgetry. Here also, the compass should stay stable.

On top of that, the Air Glide S sensor box should be fixed exactly in flight axis and without any big elevation angle error (positive or negative) relative to the plane in even flight attitude. Sure, you will not be able to attain that with absolute accuracy. Small errors in azimuth are compensated by the algorithm described further down, small errors in elevation are not compensated but they are not really relevant. They do lead to a horizon picture in the Air Glide S display where the horizon is a bit high or low, but they do not prevent the AHRS from working.

Next step is the compass compensation flight : A pattern of 8, starting in direction north. Start with a full circle left at 40° bank. When reaching north again, immediately start another circle to the right at 40° bank. As you fly through the pattern the compass compensation quality indication should climb from 0 to 9. It might even go up and down a bit, but it should end at 8 or 9 when you are through the second circle and you straighten out for a north course again. The Air Glide S will eventually say "compensated" and it squeaks a bit, as the Kalman filters get new starting values and have to adjust. The system needs about 15 minutes to completely stabilize after the compensation before it becomes fully reliable. The Kalman filters are adaptive, that is to say the output of the inertial platform is getting better with usage time.

You may check at once if the compensation was truly successful. Go to the horizon page, it should show an even horizon. If the horizon is askew, the compensation was no good.

Don't be afraid when the compensation does not work the first time. Do it again. Only if after 5 tries you do not reach 8 or 9 as quality factor, look for a different location for the box or think about interfering factors which could be eliminated. After many trials I had to ban my AirPath compass from the cockpit. It always messed up the compensation. It took a while to find out.

When, after you gave the system half an hour to settle, you fly an docile circle in calm air, you should see the wind arrow smoothly turn with your circle, and the wind speed should not vary by more than +-3 km/h.

If the speed varies in a larger interval then you should consider using the IAS-CAS correction possibilities (see at the very end of the paper). It might happen that the total pressure measurement in your ship is a tiny bit off (it is so in most ships). There are two error sources for that :

The air mass flowing along the fuselage is accelerated by the volume dislocation of the fuselage and it might still be a tiny bit fast in relation to the non-disturbed air around your ship when it hits the fin probe.

If on your plane's static and total pressures happen to be taken from the nose and the side of the fuselage, there is a systematic mismeasurement of your plane's speed (most plane types show this behaviour, check your Owner's Flight Manual).

When CAS at the sensor input is too big, then in the downwind part of a circle the wind will be calculated as too small, vice versa in the headwind part of the circle as too big.

All further preparations of the Air Glide S are done by configurations in the various SETUP-menus of the variometer. Be warned. It is easily possible to misconfigure the device in such a way that it can be rendered pretty much useless in flight. However, the below set of baseline setup values will give you acceptable results right away and you can always fall back to these values.

This warning should not stop you from modifying and potentially optimising these values for your aircraft and flying style as you get acquainted with understanding how settings work and interact.

Vario	Vario	Vario
Vario Filter	Sollfahrtfehler Filter	Flugzeug
4.0 s	0.0 s	DGneu
Luftmasse Filter	Luftmasse Mixer	Gleitzahl Mittelwert Zeit
4.0 s	50 %	30.0 s
Vario Mittelwert Zeit	Wind Filter	TE Kompensation
30.0 s	30.0 s	100.0 %
Luftmasse Mittelw. Zeit	Flugzeug	Vario Mode
15.0 s	DGneu	Manuell
Sollfahrtfehler Filter	Gleitzahl Mittelwert Zeit	Höhenreserve
0.0 s	30.0 s	100 m
Vario Filter-Zeitkonstante.	LD AVG Zeitkonstante.	Höhenreserve bei Ankun

# Menue : Setup / Vario

# First picture :

Speed command error filter set to 0.0 sec !! In this way the current SC indication works best – IMHO.

I am not happy with the SC signal behavior and I am in constant discussion with Butterfly about this issue. I do hope there will be improvements soon.

# Third picture :

The plane "DGNeu" is from my own collection of polar curves (glider.xml). If you have no file "glider.xml" on the USB stick in subdirectory <polars>, then Butterfly uses a built-in collection of polar curves from which you can choose. The DG800 polar curve in that collection seemed a bit conservative for my taste. So I replaced it.

# TE Kompensation 100.0 % means electronic compensation by total pressure.

0 % means "compensation via TE probe". All values between -10 and 100 % are possible, indicating the mixture between the compensation sources. Butterfly recommends values of 100 % for electronic compensation and between -10 to +10 % for TE compensation (al gusto).

### Menue : Setup / Voice



First picture :

SF Vario tunes ....

When selected, the SC audio is replaced by vario audio tunes during climb in cruise mode.

There are three possible criteria to decide when the SC tune is replaced by the audio tune – or you can select "no tune replacement" and you will always listen to the pipiep-pipiep-SC-audio signal.

## Menue : Setup / Voice in General and Setup / Voice Timing



#### Menue : Setup / Voice / Limits



# Menue : Setup / Logger



#### Menue : Setup / NMEA Einheit

and the second
NMEA Einheit
COM Baudrate
38400
FLARM
AUS
GPS
EIN
VARIO
CAI
LX Polare Ref-Masse
300 kg Baudrate der RS232 Schnitts

#### Menue : Setup / Gerät und Info-Boxen



#### Menue : Setup / Peripherie

Peripherie		Peripherie	. ,
SF Schalter	Ť	Mute Schalter	1
Normal		N/A	
FW Schalter	1	FLARM	1
Invertiert		N/A	
BK Schalter	1	WIFI	1
Invertiert		N/A	
Mute Schalter	1	Lautsprecher	1
N/A		R	
FLARM	1	Aussentemp. Sensor	1
N/A		Ja	
V. Mode: vario		Aussentemperatur Ser	isor.

# Menue : Setup / Route - Wegpunkte - IGC



In expert mode (press ESC then Menue):

Expert-Menue : Setup / ISU

ISU		
Magnetom	eter	Þ
Sensor Roh ON		1
V Kor @ 90	km/h	1
$-4.1\frac{\text{km}}{\text{h}}$		
V Kor @ 15 -3.1 h	50km/h	1
IAS Korrek	tur bei 90	)km/h

IAS – CAS correction